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Tunneling of the hard-core model on finite triangular lattices

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Funding information

This research was supported by the NWO via the grants 639.033.413 and 680.50.1529.

Abstract

We consider the hard-core model on finite triangular lattices with Metropolis dynamics. Under suitable conditions on the triangular lattice sizes, this interacting particle system has 3 maximum-occupancy configurations and we investigate its high-fugacity behavior by studying tunneling times, that is, the first hitting times between these maximum-occupancy configurations, and the mixing time. The proof method relies on the analysis of the corresponding state space using geometrical and combinatorial properties of the hard-core configurations on finite triangular lattices, in combination with known results for first hitting times of Metropolis Markov chains in the equivalent zero-temperature limit. In particular, we show how the order of magnitude of the expected tunneling times depends on the triangular lattice sizes in the low-temperature regime and prove the asymptotic exponentiality of the rescaled tunneling time leveraging the intrinsic symmetry of the state space.

KEYWORDS

finite triangular lattice, hard-core model, Metropolis dynamics, mixing time, tunneling time.

1 | INTRODUCTION

The *hard-core model* was introduced in the chemistry and statistical physics literature to describe the behavior of a gas whose particles have non-negligible radii and cannot overlap [10, 21, 22].

A finite undirected graph $\Lambda = (V, E)$ describes the spatial structure of the finite volume in which the particles interact. More specifically, the vertices represent the possible sites where particles can reside, while the hard-core constraints are represented by edges connecting the pairs of sites that cannot be occupied simultaneously. Particle configurations that do not violate these hard-core constraints are

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then in one-to-one correspondence with the independent sets of the graph Λ , whose collection we denote by $\mathcal{I}(\Lambda)$. Given $\lambda > 0$, the *hard-core measure with activity* (or *fugacity*) λ is the probability measure on $\mathcal{I}(\Lambda)$ defined by

$$\pi_{\lambda}(I) := \frac{\lambda^{|I|}}{Z_{\lambda}(\Lambda)}, \quad I \in \mathcal{I}(\Lambda), \tag{1}$$

where $Z_{\lambda}(\Lambda)$ is the appropriate normalizing constant, also called *partition function*.

In this paper we focus on the *dynamics* of particles with hard-core repulsion on *finite* graphs. The evolution over time of this interacting particle system is described by a reversible single-site update Markov chain $\{X_t\}_{t\in\mathbb{N}}$ with Metropolis transition probabilities, parametrized by the fugacity $\lambda \ge 1$. More precisely, at every step a site is selected uniformly at random; if such a site is unoccupied, then a particle is placed there with probability 1 if and only if all the neighboring sites are also unoccupied; if instead the selected site is occupied, the particle is removed with probability $1/\lambda$.

Other single-site update dynamics (eg, Glauber dynamics) for the hard-core model have received a lot of attention in the discrete mathematics community [2, 6–9, 12, 16, 19], where they are instrumental to sample weighted independent sets. Aiming to understand the performance of this local Markov chain Monte Carlo method, the main focus of this literature is on *mixing times* and on how they scale in the graph size. Indeed, the behavior of these MCMC changes dramatically as the fugacity λ grows, going from a fast convergence to stationarity ("*fast mixing*") to an exponentially slow one ("*slow mixing*"); this phenomenon is intimately related to the aforementioned phase transition phenomenon of the hard-core model on infinite graphs.

The main focus of the present paper is on the hard-core particle dynamics $\{X_t\}_{t\in\mathbb{N}}$ on finite graphs when the fugacity grows large, that is, $\lambda \to \infty$. In this regime, the hard-core measure (1) favors configurations with a maximum number of particles and we are interested in describing the *tunneling behavior* of such a particle system, that is, how it evolves between these maximum-occupancy configurations. To understand the transient behavior of the hard-core model in the high-fugacity regime, we study the asymptotic behavior of the *first hitting times* of the Markov chain $\{X_t\}_{t\in\mathbb{N}}$ between the maximum-occupancy configurations, which tell us how "rigid" they are and how long it takes for the particle system to "switch" between them.

The hard-core model has been successfully used to model certain random-access protocols for wireless networks [5, 23, 24]. In this context understanding the tunneling behavior of the hard-core model is instrumental to analyze *temporal starvation phenomena* for these communication networks and their impact on performance [28].

Tunneling phenomena of the hard-core model have already been studied on complete partite graphs [26, 27] and on square grid graphs [20]. In this work we focus on the case where Λ is a *finite triangular lattice*. Imposing periodic boundary conditions, there are 3 maximum-occupancy configurations on such graphs, as illustrated in Figure 1. These 3 hard-core configurations, denoted as **a**, **b**, and **c**, correspond to the tripartition of Λ .

As the fugacity grows large, this particle system spends roughly one third of the time in each of these 3 configurations. However, it takes a long time for the Markov chain $\{X_t\}_{t\in\mathbb{N}}$ to move from one maximum-occupancy configuration to another, since such a transition involves the occurrence of rare events. Intuitively, along any such a transition, the Markov chain must follow a path through mixed-activity particle patterns that, having fewer particles, are highly unlikely in view of (1) and the time to reach such configurations is correspondingly long.

By introducing the *inverse temperature* $\beta = \log \lambda$ and an appropriate Hamiltonian, the Markov chain $\{X_t\}_{t \in \mathbb{N}}$ can be seen as a Freidlin-Wentzell Markov chain with Metropolis transition probabilities and the hard-core measure (1) rewrites as a Gibbs distribution. In this setting, the high-fugacity

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FIGURE 1 The 3 maximum-occupancy configurations **a**, **b**, and **c** on the 6×9 triangular lattice [Color figure can be viewed at wileyonlinelibrary.com]

regime in which we are interested corresponds to the low-temperature limit $\beta \rightarrow \infty$ and the maximum-occupancy configurations are the *stable configurations* of the system, that is, the global minima of the Hamiltonian.

This identification allow us to use the *pathwise approach* [3, 17], a framework that has been successfully used to study metastability problem for many finite-volume models in a low-temperature regime. In this paper we mostly make use of the extension of the classical pathwise approach developed in [20] that covers the case of *tunneling times*. The crucial idea behind this method is to understand which paths the Markov chain most likely follows in the low-temperature regime and derive from them asymptotic results for hitting times. For Freidlin-Wentzell Markov chains this can be done by analyzing the *energy landscape* to find the paths between the initial and the target configurations with a minimum energy barrier. In the case of the tunneling times between stable configurations of the hard-core model, this problem reduces to identifying the most efficient way, starting from a stable configuration to progressively add the particles present in the target stable configuration.

By exploring detailed geometric properties of the mixed-activity hard-core configurations on finite triangular lattices, we develop a novel combinatorial method to quantify their "energy inefficiency" and obtain in this way the *minimum energy barrier* $\Gamma(\Lambda) > 0$ that has to be overcome in the energy landscape for the required transition to occur. In particular, we show how this minimum energy barrier $\Gamma(\Lambda)$ depends on the sizes of the finite triangular lattice Λ . In our main result we characterize the asymptotic behavior for the tunneling times between stable configurations giving sharp bounds in probability and proving that the order of magnitude of their expected values is equal to $\Gamma(\Lambda)$ on a logarithmic scale. Furthermore, we prove that the tunneling times scaled by their expected values are exponentially distributed in the low-temperature limit, leveraging in a nontrivial way the intrinsic symmetry of the energy landscape.

Lastly, using structural properties of the energy landscapes and classical results [4, 18] for Freidlin-Wentzell Markov chains, we show that the timescale $\lambda^{\Gamma(\Lambda)} = e^{\beta\Gamma(\Lambda)}$ at which transitions between maximum-occupancy configurations most likely occur is also the order of magnitude of the *mixing time* of the Markov chain $\{X_t\}_{t\in\mathbb{N}}$, proving that the hard-core dynamics exhibit *slow mixing* on finite triangular lattices.



FIGURE 2 The 6×9 triangular grid A and its 3 components highlighted using different colors

2 | MODEL DESCRIPTION AND MAIN RESULTS

We consider the hard-core model on finite triangular lattices with periodic boundary conditions. More precisely, given 2 integers $K \ge 2$ and $L \ge 1$, we consider the $2K \times 3L$ triangular grid Λ , that is the subgraph of the triangular lattice consisting of N := |V| = 6KL sites placed on 2K rows of 3L sites each, see Figure 2. We impose periodic boundary conditions on Λ to preserve symmetry: indeed this choice makes Λ a vertex-transitive graph in which every vertex has the same local neighborhood. The triangular grid Λ has a natural tri-partition $V = V_a \cup V_b \cup V_c$, which is highlighted in Figure 2 by coloring the 3 components in gray, black, and white, respectively. Thanks to the chosen sizes, the 3 components of Λ have the same number of sites

$$|V_{\mathbf{a}}| = |V_{\mathbf{b}}| = |V_{\mathbf{c}}| = \frac{N}{3} = 2KL.$$
 (2)

A particle configuration on Λ is a map $\sigma : V \to \{0, 1\}$, in which we set $\sigma(v) = 1$ when the site v is occupied and $\sigma(v) = 0$ otherwise. A particle configuration on Λ is a *hard-core configuration* if $\sigma(v)\sigma(w) = 0$ for every pair of neighboring sites v, w. We denote by $\mathcal{X} \subset \{0, 1\}^N$ the set of all hard-core configurations on Λ .

Let \mathbf{a}, \mathbf{b} and \mathbf{c} be the hard-core configurations on the triangular grid Λ defined as

 $\mathbf{a}(v) := \mathbb{1}_{\{v \in V_{\mathbf{a}}\}}(v), \quad \mathbf{b}(v) := \mathbb{1}_{\{v \in V_{\mathbf{b}}\}}(v), \text{ and } \mathbf{c}(v) := \mathbb{1}_{\{v \in V_{\mathbf{c}}\}}(v).$

In section 3 we show that **a**, **b** and **c** are the maximum-occupancy configurations of the hard-core model on Λ .

We are interested in studying the Metropolis dynamics for such a model, that is the family of Markov chains $\{X_t^{\beta}\}_{t \in \mathbb{N}}$ on \mathcal{X} parametrized by the inverse temperature $\beta > 0$ with transition probabilities

$$P_{\beta}(\sigma, \sigma') := \begin{cases} Q(\sigma, \sigma')e^{-\beta[H(\sigma') - H(\sigma)]^{+}}, & \text{if } \sigma \neq \sigma', \\ 1 - \sum_{\eta \neq \sigma} P_{\beta}(\sigma, \eta), & \text{if } \sigma = \sigma', \end{cases}$$

where the *connectivity function* $Q : \{(\sigma, \sigma') \in \mathcal{X} \times \mathcal{X} : \sigma \neq \sigma'\} \rightarrow [0, 1]$ allows only single-site updates:

$$Q(\sigma, \sigma') := \begin{cases} \frac{1}{N}, & \text{if } |\{v \in V : \sigma(v) \neq \sigma'(v)\}| = 1, \\ 0, & \text{if } |\{v \in V : \sigma(v) \neq \sigma'(v)\}| > 1, \end{cases}$$
(3)

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and $H : \mathcal{X} \to \mathbb{R}$ is the *energy function* or *Hamiltonian* defined as

$$H(\sigma) := -\sum_{v \in V} \sigma(v).$$
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In other words, each configuration $\sigma \in \mathcal{X}$ is assigned an *energy* $H(\sigma)$ proportional to the total number of particles in σ . We remark that here the energy of a hard-core configuration does not describe the interaction potential between particles, which is already fully captured by the set \mathcal{X} of hard-core configurations on Λ .

The triplet (\mathcal{X}, H, Q) is called *energy landscape* and we denote by \mathcal{X}^s the set of *stable configurations* of the energy landscape, that is the set of global minima of H on \mathcal{X} . Since \mathcal{X} is finite, the set \mathcal{X}^{s} is always nonempty. The Markov chain $\{X_t^{\beta}\}_{t \in \mathbb{N}}$ is reversible with respect to the *Gibbs measure* at inverse temperature β associated to the Hamiltonian H, namely

$$\mu_{\beta}(\sigma) := \frac{1}{Z_{\beta}} e^{-\beta H(\sigma)}, \quad \sigma \in \mathcal{X},$$

where $Z_{\beta} := \sum_{\sigma' \in \mathcal{X}} e^{-\beta H(\sigma')}$ is the normalizing partition function. Furthermore, it is well-known (eg, [4, Proposition 1.1]) that the Markov chain $\{X_t^{\beta}\}_{t \in \mathbb{N}}$ is aperiodic and irreducible on \mathcal{X} . Hence, $\{X_t^{\beta}\}_{t\in\mathbb{N}}$ is ergodic on \mathcal{X} with stationary distribution μ_{β} . For a nonempty subset $A \subset \mathcal{X}$ and a configuration $\sigma \in \mathcal{X}$, we denote by τ_A^{σ} the *first hitting time* of the subset A for the Markov chain $\{X_t^{\beta}\}_{t\in\mathbb{N}}$ with initial configuration σ at time t = 0, that is

$$\tau_A^{\sigma} := \inf \left\{ t \in \mathbb{N} : X_t^{\beta} \in A \left| X_0^{\beta} = \sigma \right\} \right\}.$$

We will refer to τ_A^{σ} as *tunneling time* if σ is a stable configuration and the target set is some $A \subseteq \mathcal{X}^s \setminus \{\sigma\}$. The first main result describes the asymptotic behavior of the tunneling times τ_b^a and $\tau_{\{b,c\}}^a$ on the triangular grid Λ in the low-temperature regime $\beta \to \infty$.

Theorem 2.1 (Asymptotic behavior of tunneling times) Consider the Metropolis Markov chain $\{X_t^{\beta}\}_{t\in\mathbb{N}}$ corresponding to the hard-core dynamics on the $2K \times 3L$ triangular grid Λ and define

$$\Gamma(\Lambda) := \min\{K, 2L\} + 1. \tag{5}$$

Then,

(i)
$$\lim_{\beta \to \infty} \mathbb{P}_{\beta} \left(e^{\beta(\Gamma(\Lambda) - \varepsilon)} \le \tau_{\mathbf{b}}^{\mathbf{a}} \le \tau_{\{\mathbf{b}, \mathbf{c}\}}^{\mathbf{a}} \le e^{\beta(\Gamma(\Lambda) + \varepsilon)} \right) = 1;$$

(ii)
$$\lim_{\beta \to \infty} \frac{1}{\beta} \log \mathbb{E} \tau_{\mathbf{b}}^{\mathbf{a}} = \Gamma(\Lambda) = \lim_{\beta \to \infty} \frac{1}{\beta} \log \mathbb{E} \tau_{\{\mathbf{b}, \mathbf{c}\}}^{\mathbf{a}};$$

(iii)
$$\frac{\tau_{\{\mathbf{b}, \mathbf{c}\}}^{\mathbf{a}}}{\mathbb{E} \tau_{\mathbf{b}}^{\mathbf{a}}} \xrightarrow{d} \operatorname{Exp}(1), \quad \text{as } \beta \to \infty;$$

(iii)
$$\frac{\pi^{a}}{\mathbb{E}\tau^{a}_{b,c}} \xrightarrow{\rightarrow} \operatorname{Exp}(1), \quad \text{as } p \rightarrow 0$$

(iv) $\frac{\tau^{a}_{b}}{\mathbb{E}\tau^{a}_{b}} \xrightarrow{\rightarrow} \operatorname{Exp}(1), \quad \text{as } \beta \rightarrow \infty.$

The proofs of statements (i), (ii), and (iii) of the latter theorem are presented in section 4 and leverage the general framework for hitting time asymptotics developed in [20] in combination with the analysis of the energy landscape corresponding to the hard-core model on the triangular grid Λ to which section 3 is devoted.

As established by the next theorem, which is our second main result, the structural properties of the energy landscapes that will be presented in section 3 also yield the following result for the *mixing time*.

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Recall that the mixing time describes the time required for the distance (measured in total variation) to stationarity to become small. More precisely, for every $0 < \epsilon < 1$, we define the *mixing time* $t_{\alpha}^{mix}(\epsilon)$ by

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$$t_{\beta}^{\min}(\varepsilon) := \min\{n \ge 0 : \max_{\sigma \in \mathcal{X}} \|P_{\beta}^{n}(\sigma, \cdot) - \mu_{\beta}(\cdot)\|_{\mathrm{TV}} \le \varepsilon\},\$$

where $\|v - v'\|_{\text{TV}} := \frac{1}{2} \sum_{\sigma \in \mathcal{X}} |v(\sigma) - v'(\sigma)|$ for any 2 probability distributions v, v' on \mathcal{X} . Another classical notion to investigate the speed of convergence of Markov chains is the *spectral gap*, which is defined as $\rho_{\beta} := 1 - \alpha_2$, where $1 = \alpha_1 > \alpha_2 \ge \cdots \ge \alpha_{|\mathcal{X}|} \ge -1$ are the eigenvalues of the matrix $(P_{\beta}(\sigma, \sigma'))_{\sigma, \sigma' \in \mathcal{X}}$. The spectral gap can be equivalently defined using the Dirichlet form associated with the pair (P_{β}, μ_{β}) , see [15, Lemma 13.12].

Theorem 2.2 (Mixing time and spectral gap) Consider the Metropolis Markov chain $\{X_t^{\beta}\}_{t \in \mathbb{N}}$ corresponding to the hard-core dynamics on the $2K \times 3L$ triangular grid Λ and define $\Gamma(\Lambda)$ as in (5). Then, for any $0 < \varepsilon < 1$,

$$\lim_{\beta \to \infty} \frac{1}{\beta} \log t_{\beta}^{\min}(\varepsilon) = \Gamma(\Lambda).$$

Furthermore, there exist 2 positive constants $0 < c_1 \le c_2 < \infty$ independent of β such that the spectral gap ρ_β of the Markov chain $\{X_t^\beta\}_{t\in\mathbb{N}}$ satisfies

$$c_1 e^{-\beta\Gamma(\Lambda)} \le \rho_\beta \le c_2 e^{-\beta\Gamma(\Lambda)} \qquad \forall \beta \ge 0.$$

Therefore, the mixing time turns out to be asymptotically of the same order of magnitude as the tunneling time between stable configurations, establishing the *slow mixing* of $\{X_t^\beta\}_{t\in\mathbb{N}}$ as $\beta \to \infty$. We remark that mixing times for the hard-core model with Glauber dynamics have received a lot of attention in the literature, see, for example, [2, 8, 9] and, in particular, [11] for results for triangular grids, but, differently from the present paper, these works focus mostly on identifying how the mixing time scales with the graph size at fixed temperature/fugacity.

Different choices for the sizes of the triangular grid or for the boundary conditions result in a fundamentally different geometry of the stable configurations and thus completely change the energy landscape. For example, (i) the 4×6 triangular grid with open boundary conditions is still a tripartite graph, but has 63 stable configurations; (ii) the 4×4 and 4×5 triangular grids with periodic boundary conditions are not tripartite anymore (being both 4-partite graphs) and have 32 and 10 stable configurations, respectively; (iii) the 5×5 triangular grid with open boundary conditions is 4-partite and has a unique stable configuration. A complete characterization of the stable configurations of these triangular grids and of the (probably heterogeneous) energy barriers separating them seems very involved and is only the first step of the energy landscape analysis, leaving little hope that our results could be easily generalized to such scenarios.

The rest of the paper is organized as follows. Section 3 is entirely devoted to analysis of geometrical and combinatorial properties of the hard-core configurations on triangular grids and to the derivation of the structural properties of the energy landscape, which will then be used in section 4 to prove the two main theorems.

3 | ENERGY LANDSCAPE ANALYSIS

This section is devoted to the analysis of the energy landscape associated with the hard-core dynamics on the $2K \times 3L$ triangular grid Λ . Leveraging geometrical features of the hard-core configurations on

A, we prove crucial structural properties of the corresponding energy landscape (\mathcal{X}, H, Q) , as stated in Theorem 3.1 below.

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In the rest of this paper, we will use the same notions and notation introduced in [20]. The connectivity matrix Q given in (3) is irreducible, that is, for any pair of configurations $\sigma, \sigma' \in \mathcal{X}, \sigma \neq \sigma'$, there exists a finite sequence ω of configurations $\omega_1, \ldots, \omega_n \in \mathcal{X}$ such that $\omega_1 = \sigma, \omega_n = \sigma'$ and $Q(\omega_i, \omega_{i+1}) > 0$, for $i = 1, \ldots, n - 1$. We refer to such a sequence as a *path* from σ to σ' and denote it by $\omega : \sigma \to \sigma'$. Given a path $\omega = (\omega_1, \ldots, \omega_n)$, we define its *height* Φ_{ω} as $\Phi_{\omega} := \max_{i=1,\ldots,n} H(\omega_i)$. The *communication height* between a pair of configurations $\sigma, \sigma' \in \mathcal{X}$ is defined as

$$\Phi(\sigma, \sigma') := \min_{\omega: \sigma \to \sigma'} \Phi_{\omega} = \min_{\omega: \sigma \to \sigma'} \max_{i=1, \dots, |\omega|} H(\omega_i),$$

and its natural extension to disjoint non-empty subsets $A, B \subset \mathcal{X}$ is

$$\Phi(A,B) := \min_{\sigma \in A, \, \sigma' \in B} \Phi(\sigma,\sigma').$$

The next theorem summarizes the structural properties of the energy landscape corresponding to the hard-core dynamics on a triangular grid Λ . More specifically, (i) we prove that **a**, **b** and **c** are the only 3 stable configurations, (ii) find the value of the communication height between them, as a function of the triangular grid sizes *K* and *L*, and (iii) show by means of 2 iterative algorithms that there is "*absence of deep cycles*" (see condition (25) below) in the energy landscape (\mathcal{X}, H, Q).

Theorem 3.1 (Structural properties of the energy landscape) Let (\mathcal{X}, H, Q) be the energy landscape corresponding to the hard-core dynamics on the $2K \times 3L$ triangular grid Λ with $K \ge 2$ and $L \ge 1$. Then,

- (i) $\mathcal{X}^{s} = \{a, b, c\};$
- (ii) $\Phi(\mathbf{a}, \mathbf{b}) H(\mathbf{a}) = \Phi(\mathbf{a}, \mathbf{c}) H(\mathbf{a}) = \Phi(\mathbf{b}, \mathbf{c}) H(\mathbf{b}) = \min\{K, 2L\} + 1;$
- (iii) $\Phi(\sigma, \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}) H(\sigma) \le \min\{K, 2L\} \quad \forall \sigma \in \mathcal{X} \setminus \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}.$

Note that identity (ii) in Theorem 3.1 motivates the definition (5) of $\Gamma(\Lambda)$ in Theorem 2.1.

We briefly outline here the proof strategy of Theorem 3.1, to which is devoted the rest of this section. As illustrated by the state space diagram in Figure 3, there is not a unique bottleneck separating the stable configurations (this was the case for complete partite graphs [26, 27]) and there are in fact exponentially many possible ways for the Markov chain $\{X_t^{\beta}\}_{t\in\mathbb{N}}$ to make such transitions. This makes the task of identifying the energy barrier between stable configurations much harder.

Inspired by the ideas in Greenberg and Randall [12] and by the methodology used for square grids in [20] we tackle this problem by looking at geometric features of the hard-core configurations on triangular grids. In section 3.1, after some preliminary definitions, we study the combinatorial properties of hard-core configurations on horizontal and vertical *stripes* of the triangular grid Λ , that is, pairs of adjacent rows (triplets of adjacent columns, respectively). In particular, we find the maximum number of particles that a hard-core configuration can have in a horizontal stripe and characterize how particles are arranged on such stripes in Lemma 3.3. Theorem 3.1(i) is an almost immediate consequence of these combinatorial results. Afterwards, using further geometrical properties of the hard-core configurations, we prove Proposition 3.4, which gives the following lower bound for the communication height between **a** and **b**:

$$\Phi(\mathbf{a}, \mathbf{b}) - H(\mathbf{a}) \ge \min\{K, 2L\} + 1.$$



FIGURE 3 The energy landscape corresponding to the hard-core dynamics on the 4×6 triangular grid. The color scheme is chosen in such a way that the lighter the color of a node, the lower the energy of the corresponding configuration. [Color figure can be viewed at wileyonlinelibrary.com]

We then introduce two *energy reduction algorithms* in section 3.2, which are used in Proposition 3.5 to construct a reference path ω^* : $\mathbf{a} \rightarrow \mathbf{b}$, guaranteeing that the lower bound above is sharp, i.e.,

$$\Phi(\mathbf{a}, \mathbf{b}) - H(\mathbf{a}) = \min\{K, 2L\} + 1,$$

and concluding the proof of Theorem 3.1(ii). The same algorithms are then used again to build a path from every configuration $\sigma \notin \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}$ to the set $\{\mathbf{a}, \mathbf{b}, \mathbf{c}\}$ with a prescribed energy height, obtaining in this way the inequality stated in Theorem 3.1(iii).

3.1 | Geometrical properties of hard-core configurations

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We first introduce some useful definitions to describe hard-core configurations on the triangular grid Λ . Denote by c_j , j = 0, ..., 6L - 1, the *j*-th column of Λ , and by r_i , i = 0, ..., 2K - 1, the *i*-th row of Λ , see Figure 4. In the rest of the paper, the row and column indices should always be taken modulo 2K and 6L, respectively.

Note that every row has an equal number of sites from each component, since

$$|r_i \cap V_{\mathbf{a}}| = |r_i \cap V_{\mathbf{b}}| = |r_i \cap V_{\mathbf{c}}| = L \qquad \forall i = 0, \dots, 2K - 1,$$
(6)



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FIGURE 4 Illustration of row, column and stripe notation for the triangular grid



FIGURE 5 Illustration of horizontal and vertical stripes in which the sites' tripartition is highlighted using different colors

while each column consists of sites from a single component, and, in fact,

$$V_{\mathbf{a}} = \bigcup_{j=0}^{L-1} c_{3j}, \quad V_{\mathbf{b}} = \bigcup_{j=0}^{L-1} c_{3j+1}, \quad \text{and} \quad V_{\mathbf{c}} = \bigcup_{j=0}^{L-1} c_{3j+2}.$$
(7)

Each site $v \in V$ lies at the intersection of a row with a column and we associate to v the coordinates (i, j) if $v = r_j \cap c_i$. We call the collection of sites belonging to 2 adjacent rows a *horizontal stripe*. In particular, we denote by S_i , with i = 0, ..., K - 1, the horizontal stripe consisting of rows r_{2i} and r_{2i+1} , that is, $S_i := r_{2i} \cup r_{2i+1}$, see Figure 4. When the index of a stripe is not relevant, we will simply denote it by S. We define a *vertical stripe* to be the collection of sites belonging to 3 adjacent columns, which we denote by C in general. In particular, for j = 0, ..., 3L - 1 we denote by C_j the vertical stripe consisting of columns c_j, c_{j+1} and c_{j+2} , see Figure 4. For every horizontal stripe S note that |S| = 6L and (6) implies that $|S \cap V_{\mathbf{a}}| = |S \cap V_{\mathbf{b}}| = |S \cap V_{\mathbf{c}}| = 2L$, see also Figure 5A where we highlight the tripartition of a horizontal stripe. Similarly, for every vertical stripe C, we have |C| = 3K and, in view of (7), we have $|C \cap V_{\mathbf{a}}| = |C \cap V_{\mathbf{b}}| = |C \cap V_{\mathbf{c}}| = K$. A special role will be played by the vertical stripes whose middle column belongs to $V_{\mathbf{b}}$, which are those of the form C_{3j} for some j = 0, ..., 2L-1, whose structure is displayed in Figure 5B,C.

$$\Delta H(\sigma) := H(\sigma) - H(\mathbf{a}). \tag{8}$$

In view of the fact that $H(\mathbf{a}) = H(\mathbf{b}) = H(\mathbf{c}) = -2KL$ and the definition (4) of $H(\cdot)$, we can rewrite

$$\Delta H(\sigma) = 2KL - \sum_{v \in V} \sigma(v).$$

A subset of sites $W \subseteq V$ is said to be *balanced* if $|W \cap \Lambda_{\mathbf{a}}| = |W \cap \Lambda_{\mathbf{b}}| = |W \cap \Lambda_{\mathbf{c}}|$. The energy difference of a configuration $\sigma \in \mathcal{X}$ on a balanced subset $W \subseteq V$ is defined as by $\Delta H_W(\sigma) := |W \cap \Lambda_{\mathbf{a}}| - \sum_{v \in W} \sigma(v)$. Note that the horizontal and vertical stripes are balanced subsets and that energy difference $\Delta H(\sigma)$ in (8) can be written as the sum of the energy differences on non-overlapping horizontal/vertical stripes, that is

$$\Delta H(\sigma) = \sum_{i=0}^{K-1} \Delta H_{S_i}(\sigma) = \sum_{j=0}^{2L-1} \Delta H_{C_{3j}}(\sigma) = \sum_{j=0}^{2L-1} \Delta H_{C_{3j+1}}(\sigma) = \sum_{j=0}^{2L-1} \Delta H_{C_{3j+2}}(\sigma).$$
(9)

We adopt the following coloring convention for displaying a hard-core configuration $\sigma \in \mathcal{X}$: We put a node in site $v \in V$ if it is occupied, that is, $\sigma(v) = 1$, and we color it gray, black, or white depending on whether the site v belongs to V_a , V_b , V_c respectively; if a site $v \in V$ is unoccupied, that is, $\sigma(v) = 0$, we do not display any node there.

There is an equivalent way to represent hard-core configurations on Λ . Consider the 12*KL* triangular faces of the graph Λ , to which we will simply refer as *triangles*. Each triangle can have at most one occupied site in its 3 vertices (them being a clique of the graph Λ); if this is the case, then we refer to it as *blocked triangle* and color it as gray, black, or with a dotted pattern, depending on whether such particle belongs to V_a , V_b or V_c , respectively. Otherwise, if none of its 3 vertices is occupied by a particle, we call a triangle *free* and leave it blank. In the rest of the paper, we will use a "mixed" representation for hard-core configurations on Λ , displaying both the occupied sites and the corresponding blocked triangles with the aforementioned coloring schemes, see Figure 6 for an example.

Since each site is the vertex of 6 triangles on Λ , placing particles with hard-core constraints on a triangular grid corresponds to placing hexagons without overlaps on the same lattice. This is the reason why the hard-core model on the triangular lattice is often called *hard-hexagon model* in the statistical physics literature.



FIGURE 6 An example of a hard-core configuration σ on the 6 \times 9 triangular grid



FIGURE 7 All possible local hard-core configurations in which 2 blocked triangles share an edge



FIGURE 8 Examples of hard-core configurations displaying bridges on the 6 × 9 triangular grid [Color figure can be viewed at wileyonlinelibrary.com]

Remark 1. A key observation is that blocked triangles sharing an edge must be of the same color. Indeed, as illustrated in Figure 7, if a particle resides in one of the 2 endpoints of that edge, they trivially are of the same color by construction. Otherwise, there must be a particle in each of the 2 vertices that are not shared by the 2 triangles (as they are both assumed to be blocked). It is easy to check that these 2 vertices always belong to the same partition (cf. Figure 7), yielding the same coloring for the 2 triangles under consideration.

Given 2 configurations $\sigma, \sigma' \in \mathcal{X}$ and a subset of sites $W \subseteq V$, we write

$$\sigma_{|W} = \sigma'_{|W} \quad \Longleftrightarrow \quad \sigma(v) = \sigma'(v) \quad \forall v \in W.$$

We say that a configuration $\sigma \in \mathcal{X}$ has a *horizontal* \mathbf{a} -(\mathbf{b} -, \mathbf{c} -)*bridge* in stripe *S* if σ perfectly agrees there with \mathbf{a} (respectively \mathbf{b} , \mathbf{c}), that is $\sigma_{|S} = \mathbf{a}_{|S}$ (respectively $\sigma_{|S} = \mathbf{b}_{|S}$ or $\sigma_{|S} = \mathbf{c}_{|S}$). Similarly, we say that $\sigma \in \mathcal{X}$ has a *vertical* \mathbf{a} -(\mathbf{b} -, \mathbf{c} -)*bridge* in stripe *C* if σ perfectly agrees there with \mathbf{a} (respectively \mathbf{b} , \mathbf{c}), that is $\sigma_{|C} = \mathbf{a}_{|C}$ (respectively $\sigma_{|C} = \mathbf{b}_{|C}$ or $\sigma_{|C} = \mathbf{c}_{|C}$). We informally say that 2 bridges are of the same *color* when they agree with the same stable configuration. Two examples of bridges are shown in Figure 8A,B.

Lemma 3.2 (Geometric features of hard-core configurations) A hard-core configuration $\sigma \in \mathcal{X}$ cannot display simultaneously a vertical bridge and a horizontal bridge of different colors.

Proof Assume without loss of generality that the vertical bridge is a **b**-bridge. Such a vertical bridge blocks 2 sites on every row, belonging to $V_{\mathbf{a}}$ and $V_{\mathbf{c}}$, and thus no horizontal stripe can fully agree with **a** or **c**.

It is possible, however, that a vertical and a horizontal bridges coexist when they are of the same color and this fact motivates the next definition. We say that a configuration $\sigma \in \mathcal{X}$ has a **a**-(**b**-,**c**-)*cross*

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FIGURE 9 Example of a hard-core configuration displaying a **b**-cross on the 6 × 9 triangular grid [Color figure can be viewed at wileyonlinelibrary.com]

if it has simultaneously at least 2 **a**-(**b**-,**c**-)bridges, one vertical and one horizontal; see Figure 9 for an example of a **b**-cross.

In order to prove Theorem 3.1(ii), we need the following lemma which characterizes the structure of horizontal and vertical stripes with zero energy difference.

Lemma 3.3 (Energy-efficient stripes structure) Let $\sigma \in \mathcal{X}$ be a hard-core configuration on the $2K \times 3L$ triangular grid. The following statements hold:

(i) For every horizontal stripe S, the energy difference is non-negative, that is, $\Delta H_S(\sigma) \ge 0$, and

$$\Delta H_S(\sigma) = 0 \quad \iff \quad \sigma \text{ has a horizontal bridge in stripe } S; \tag{10}$$

(ii) For every vertical stripe C of the form $C = C_{3j}$, the energy difference is non-negative, that is $\Delta H_C(\sigma) \ge 0$. Furthermore, if σ has at least one black particle on C, i.e., $\sum_{v \in C \cap V_b} \sigma(v) > 0$, then

$$\Delta H_C(\sigma) = 0 \quad \iff \quad \sigma \text{ has a vertical } \mathbf{b}\text{-bridge in stripe } C. \tag{11}$$

Proof In this proof we leverage the equivalent representation of a hard-core configuration as collection of blocked triangles. The underlying idea for horizontal and vertical stripes is the same, but we present the proof separately in view of their different structures.

(i) Given $\sigma \in \mathcal{X}$, denote by $b_S(\sigma)$ and $f_S(\sigma)$ the number of blocked triangles and of free triangles on the horizontal stripe *S*, respectively. Since the total number of triangles of the horizontal stripe *S* is 6L, we have $b_S(\sigma) + f_S(\sigma) = 6L$. Furthermore, as each particle blocks exactly 3 triangles on the horizontal stripe *S*, it holds that $b_S(\sigma) = 3 \sum_{v \in S} \sigma(v)$ and, thus,

$$f_S(\sigma) = 6L - b_S(\sigma) = 3\left(2L - \sum_{v \in S} \sigma(v)\right) = 3 \cdot \Delta H_S(\sigma).$$
(12)

Since $f_S(\sigma)$ is by construction a non-negative integer, it readily follows that $\Delta H_S(\sigma) \ge 0$.

Let us now turn to the characterization (10) of the horizontal stripes with energy difference equal to zero. If $\Delta H_S(\sigma) = 0$, identity (12) gives that $f_S(\sigma) = 0$, and thus *S* has no free triangles. In view of Remark 1 and leveraging the fact that each triangle in *S* shares edges with 2 neighboring triangles, it follows by finite induction that all triangles in *S* all are of the same color and, hence, either $\sigma_{|S} = \mathbf{a}_{|S}$ or $\sigma_{|S} = \mathbf{b}_{|S}$ or $\sigma_{|S} = \mathbf{c}_{|S}$. To prove the converse direction, note that if $\Delta H_S(\sigma) > 0$, then also $f_S(\sigma) > 0$, that is, there is at least one free triangle on *S*. Consider the sites corresponding to the 3 vertices of



FIGURE 10 Hard-core configuration and corresponding block triangles in a vertical stripe of the form C_{3j}

any such free triangle. By construction they all must be unoccupied and, belonging each to a different partition of Λ , it follows that $\sigma_{|S} \neq \mathbf{a}_{|S}, \mathbf{b}_{|S}, \mathbf{c}_{|S}$.

(ii) Consider a vertical stripe *C* of the form C_{3j} , whose middle column is a subset of $V_{\mathbf{b}}$, see Figure 10. Analogously to (i), denote by $b_C(\sigma)$ and $f_C(\sigma)$ the number of blocked triangles and of free triangles fully contained in the vertical stripe *C*, respectively. There are 2*K* such triangles in total and thus $b_C(\sigma) + f_C(\sigma) = 2K$. Any particle, regardless of which column/partition it belongs to, blocks exactly 2 of these triangles, as illustrated in Figure 10, so that $b_C(\sigma) = 2\sum_{v \in C} \sigma(v)$ and, hence,

$$f_C(\sigma) = 2K - b_C(\sigma) = 2\left(K - \sum_{v \in C} \sigma(v)\right) = 2 \cdot \Delta H_C(\sigma).$$
(13)

The latter identity readily implies that $\Delta H_C(\sigma) \ge 0$, since $f_C(\sigma)$ is by construction a non-negative integer.

If $\Delta H_C(\sigma) > 0$, then it follows from (13) that there is at least one free triangle fully contained in stripe *C*. The 3 sites of any such free triangle, each belonging to a different partition of Λ , must be all unoccupied and thus there cannot be a vertical bridge on *C*. For the reverse implication we argue as follows. By assumption there is at least one black particle and, therefore, 2 blocked black triangles on *C*. If $\Delta H_C(\sigma) = 0$, then there are $f_C(\sigma) = 0$ free triangles on *C* in view of (13). Remark 1 states that blocked triangles sharing an edge must be of the same color (cf. the rightmost case of Figure 7), it readily follows by finite induction that all the triangles on *C* are black, which means that all the sites in column c_{3j+1} must be occupied, yielding $\sigma_{|C} \equiv \mathbf{b}_{|C}$.

We are now ready to state and prove the lower bound on the communication height between any pair of stable configurations.

Proposition 3.4 (Lower bound on the communication height between **a** and **b**) *The communication height between* **a** *and* **b** *in the energy landscape corresponding to the hard-core model on the* $2K \times 3L$ *triangular grid satisfies the following inequality*

$$\Phi(\mathbf{a}, \mathbf{b}) - H(\mathbf{a}) \ge \min\{K, 2L\} + 1.$$

Proof We will show that in every path $\omega : \mathbf{a} \to \mathbf{b}$ there exists at least one configuration with energy difference greater than or equal to min{K, 2L} + 1. Consider a path $\omega = (\omega_1, \dots, \omega_n)$ from **a** to **b**.

Without loss of generality, we may assume that there are no void moves in ω , that is, at every step either a particle is added or a particle is removed, so that $H(\omega_{i+1}) = H(\omega_i) \pm 1$ for every $1 \le i \le n-1$. Since configuration **a** has no **b**-bridges, while **b** does, at some point along the path ω there must be a configuration which is the first to display a **b**-bridge, that is a column or a row occupied only by black particles. Let m^* be the index corresponding to such configuration, that is

$$m^* := \{ m \le n \mid \exists i : (\omega_m)_{|r_i|} = \mathbf{b}_{|r_i|} \text{ or } \exists j : (\omega_m)_{|c_i|} = \mathbf{b}_{|c_i|} \}.$$

Since a **b**-bridge cannot be created in only 2 steps starting from **a**, we must have $m^* > 2$. We claim that

$$\max\{\Delta H(\omega_{m^*-1}), \Delta H(\omega_{m^*-2})\} \ge \min\{K, 2L\} + 1.$$

Since the addition of a single black particle cannot create more than one bridge in each direction, it is enough to consider the following 3 cases:

- (a) ω_{m^*} displays a vertical **b**-bridge only;
- (b) ω_{m^*} displays a horizontal **b**-bridge only;
- (c) ω_{m^*} displays a **b**-cross.

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For case (a), note that configuration ω_{m^*} does not have any horizontal bridge. Indeed, it cannot have a horizontal **b**-bridge, otherwise we would be in case (c), and any horizontal **a**- or **c**- bridge cannot coexist with the vertical **b**-bridge, in view of Lemma 3.2. Hence, the energy difference of every horizontal stripe is strictly positive, thanks to Lemma 3.3(i), and thus

$$\Delta H(\omega_{m^*}) = \sum_{i=0}^{K-1} \Delta H_{S_i}(\omega_{m^*}) \ge K.$$

Furthermore, configurations ω_{m^*-1} and ω_{m^*} differ in a unique site $v^* \in V_{\mathbf{b}}$, which is such that $\omega_{m^*-1}(v^*) = 0$ and $\omega_{m^*}(v^*) = 1$. Hence, $\Delta H(\omega_{m^*-1}) = \Delta H(\omega_{m^*}) + 1$ and thus

$$\Delta H(\omega_{m^*-1}) \ge K+1.$$

The argument for case (b) is similar to that of case (a). First**, configuration ω_{m^*} does not display any vertical bridge. Lemma 3.2 implies that there cannot be any vertical **a**- or **c**-bridge due to the presence of a horizontal **b**-bridge, while a vertical **b**-bridge cannot exist, otherwise there would be a **b**-cross and we would be in case (c). Every vertical stripe has at least one black particle, due to the presence of a horizontal **b**-bridge. Hence, $\Delta H_{C_j}(\omega_{m^*}) \ge 1$ for every j = 0, ..., 2L - 1 in view of Lemma 3.3(ii). Therefore,

$$\Delta H(\omega_{m^*}) = \sum_{j=0}^{2L-1} \Delta H_{C_j}(\omega_{m^*}) \ge 2L.$$

From this inequality it follows that $\Delta H(\omega_{m^*-1}) \ge 2L + 1$, because, as for case (a), the definition of m^* implies $\Delta H(\omega_{m^*-1}) = \Delta H(\omega_{m^*}) + 1$.

Consider now case (c), in which ω_{m^*} displays a **b**-cross. The presence of both a vertical and a horizontal **b**-bridge means that ω_{m^*} has a black particle in every vertical and horizontal stripe. This property is inherited by the configuration ω_{m^*-1} , since it differs from ω_{m^*} only by the removal of the black particle lying at the intersection of the vertical and horizontal bridge constituting the cross.

Furthermore, by definition of m^* , configuration ω_{m^*-1} cannot have any **b**-bridge, neither vertical nor horizontal. These 2 facts, in combination with Lemma 3.3, imply that

$$\Delta H(\omega_{m^*-1}) \ge \min\{K, 2L\}$$

If $\Delta H(\omega_{m^*-1}) \ge \min\{K, 2L\} + 1$, then the proof is completed. Otherwise, the energy difference of configuration ω_{m^*-1} is $\Delta H(\omega_{m^*-1}) = \min\{K, 2L\}$. The configuration preceding ω_{m^*-1} in the path ω satisfies

$$\Delta H(\omega_{m^*-2}) = \min\{K, 2L\} \pm 1,$$
(14)

since it differs from ω_{m^*-1} by a single site update. Suppose first that

$$\Delta H(\omega_{m^*-2}) = \min\{K, 2L\} - 1.$$
(15)

This means that ω_{m^*-2} differs from ω_{m^*-1} by the addition of a particle. Therefore, also configuration ω_{m^*-2} has at least one black particle in every horizontal stripe, that is

$$\sum_{\nu \in S_i \cap V_{\mathbf{b}}} \omega_{m^* - 2}(\nu) \ge 1 \quad \forall i = 0, \dots, K,$$
(16)

and at least one black particle in every vertical stripe, that is

$$\sum_{\nu \in C_j \cap V_{\mathbf{b}}} \omega_{m^* - 2}(\nu) \ge 1 \quad \forall j = 0, \dots, 2L - 1.$$
(17)

If $K \leq 2L$, (15) and the pigeonhole principle imply that there must be a horizontal stripe *S* such that $\Delta H_S(\omega_{m^*-2}) = 0$. In view of (16) and Lemma 3.3(i), ω_{m^*-2} must have a horizontal **b**-bridge in *S*, which contradicts the definition of m^* . When instead K > 2L, it follows from (15) that there must be a vertical stripe *C* such that $\Delta H_C(\omega_{m^*-2}) = 0$. Also in this case, (17) and Lemma 3.3(ii) imply that ω_{m^*-2} displays a vertical **b**-bridge in *C*, in contradiction with the definition of m^* . We have in this way proved that assumption (15) always leads to a contradiction, so in view of (14) we have $\Delta H(\omega_{m^*-2}) = \min\{K, 2L\} + 1$ and the proof is concluded also for case (c).

3.2 | Reference path and absence of deep cycles

In this subsection we describe an iterative procedure that constructs a path from a suitable initial configuration to a target stable configuration. We will refer to it as *energy reduction algorithm* since the yielded path ω brings the initial configuration σ to a configuration with lower (in particular, minimum) energy while guaranteeing that the energy along the path will never exceed the initial value plus 1 or 2, depending on the structure of the initial configuration. These 2 algorithmic procedures modify the initial configuration using only moves allowed by the hard-core dynamics (i.e., single-site updates) and increasingly grow a uniform cluster (aligned with the target configuration) proceeding either row by row or column by column. These 2 variations, despite being similar in spirit, will be described separately, since the structure of horizontal and vertical stripes of the triangular grid is fundamentally different. Nonetheless, the core mechanisms of both these algorithms is the same: orderly add particles aligned with the target configuration and, if necessary, remove the particles on the other 2 partitions that block the growth of such a cluster. In order for σ to be a suitable starting configuration for the energy reduction algorithm, σ should have "enough room" for such a cluster to be created, condition

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that is guaranteed when all the occupied sites in 2 adjacent rows (or columns) belong to the same partition.

Such energy reduction algorithms will be used in Proposition 3.5 to construct the reference path from **a** to **b** and to show the absence of deep cycle in the state space \mathcal{X} , the crucial step in the proof of Theorem 3.1(iii).

3.2.1 | Energy reduction algorithm by rows

We now describe in detail the energy reduction algorithm by rows with **b** as target configuration. In order for $\sigma \in \mathcal{X}$ to be a suitable initial configuration for this iterative procedure, we require that σ has no gray or white particles in the first horizontal stripe $S_0 = r_0 \cup r_1$, that is

$$\sigma(v) = 0 \quad \forall v \in S_0 \cap (V_\mathbf{a} \cup V_\mathbf{c}). \tag{18}$$

Figure 11 shows a hard-core configuration that satisfies this initial condition.

The output of this algorithm is a path ω from σ to **b**, which we construct as the concatenation of 2*K* paths $\omega^{(1)}, \ldots, \omega^{(2K)}$. For every $i = 1, \ldots, 2K$, path $\omega^{(i)}$ goes from σ_i to σ_{i+1} , where we set $\sigma_1 := \sigma$, $\sigma_{2K+1} := \mathbf{b}$ and define for $i = 2, \ldots, 2K$

$$\sigma_i(v) := \begin{cases} \mathbf{b}(v) & \text{if } v \in r_1, \dots, r_{i-1}, \\ 0 & \text{if } v \in r_i \cap (V_\mathbf{a} \cup V_\mathbf{c}), \\ \sigma(v) & \text{if } v \in r_i \cap V_\mathbf{b} \text{ or } v \in r_{i+1}, \dots, r_{2K-1}. \end{cases}$$

We now describe in detail how to construct each of the paths $\omega^{(i)}$ for i = 1, ..., 2K. Each path $\omega^{(i)} = (\omega_1^{(i)}, ..., \omega_{2L+1}^{(i)})$ comprises 2L + 1 moves (but possibly void) and is such that $\omega_1^{(i)} = \sigma_i$ and $\omega_{2L+1}^{(i)} = \sigma_{i+1}$. We start from configuration $\omega_0^{(i)} = \sigma_i$ and we repeat iteratively the following procedure for all j = 1, ..., 2L:

• If $j \equiv 1 \pmod{2}$, consider the pair of sites $v \in V_a$ and $v' \in V_c$ defined by

$$\begin{cases} v = (i+1,3j), & v' = (i+1,3j+2) & \text{if } i \equiv 0 \pmod{2}, \\ v = (i+1,3j-3), & v' = (i+1,3j-1) & \text{if } i \equiv 1 \pmod{2}. \end{cases}$$

Note that the 2 sites v and v' are always neighbors, so that only one of the 2 can be occupied.



FIGURE 11 Example of a hard-core configuration on the 6 × 9 triangular grid that satisfies (18) [Color figure can be viewed at wileyonlinelibrary.com]

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- If $\omega_j^{(i)}(v) = 0 = \omega_j^{(i)}(v')$, we set $\omega_{j+1}^{(i)} = \omega_j^{(i)}$, so $H(\omega_{j+1}^{(i)}) = H(\omega_j^{(i)})$.
- If $\omega_j^{(i)}(v) = 1$ or $\omega_j^{(i)}(v') = 1$, then we remove from configuration $\omega_j^{(i)}$ the particle in the unique occupied site between v and v', increasing the energy by 1 and obtaining in this way configuration $\omega_{i+1}^{(i)}$, which is such that $H(\omega_{i+1}^{(i)}) = H(\omega_i^{(i)}) + 1$.
- If $j \equiv 0 \pmod{2}$, consider the site $v \in V_b$ defined as

$$v = \begin{cases} (i, 3j - 2) & \text{if } i \equiv 0 \pmod{2}, \\ (i, 3j - 5) & \text{if } i \equiv 1 \pmod{2}. \end{cases}$$

- If $\omega_j^{(i)}(v) = 1$, we set $\omega_{j+1}^{(i)} = \omega_j^{(i)}$ and thus $H(\omega_{j+1}^{(i)}) = H(\omega_j^{(i)})$.
- If $\omega_j^{(i)}(v) = 0$, then we add to configuration $\omega_j^{(i)}$ a particle in site *v* decreasing the energy by 1. We obtain in this way a configuration $\omega_{j+1}^{(i)}$, which is a hard-core configuration because by construction all the first neighboring sites of *v* are unoccupied. In particular, the 2 particles residing in the 2 sites above *v* may have been removed exactly at the previous step. The new configuration has energy $H(\omega_{j+1}^{(i)}) = H(\omega_j^{(i)}) 1$.

The way the path $\omega^{(i)}$ is constructed shows that $H(\sigma_{i+1}) \leq H(\sigma_i)$ for every i = 1, ..., 2K, since the number of particles added in row r_i is greater than or equal to the number of particles removed in row r_{i+1} . Moreover, $\Phi_{\omega^{(i)}} \leq H(\sigma_i) + 1$, since along the path $\omega^{(i)}$ every particle removal (if any) is always followed by a particle addition. These 2 properties imply that the path $\omega : \sigma \to \mathbf{b}$ created by concatenating $\omega^{(1)}, \ldots, \omega^{(2K)}$ satisfies

$$\Phi_{\omega} \le H(\sigma) + 1.$$

Note that the energy reduction algorithm by rows can be tweaked in order to have either **a** or **c** as target configuration. In particular, the condition (18) for the initial configuration σ should be adjusted accordingly, requiring that σ has no black and white (black and gray, respectively) particles in the first horizontal stripe S_0 , depending on whether the target configuration is **a** or **c**, respectively.

3.2.2 | Energy reduction algorithm by columns

We now illustrate how the energy reduction algorithm by columns works choosing **b** as target configuration. Note that the procedure we are about to describe can be tweaked to yield a path with target configuration **a** or **c**, but we omit the details. If the target configuration is **b**, we require that the initial configuration $\sigma \in \mathcal{X}$ has no particles on columns c_2 and c_3 , namely

$$\sigma(v) = 0 \quad \forall v \in c_2 \cup c_3. \tag{19}$$

Since $c_2 = C_0 \cap V_c$ and $c_3 = C_1 \cap V_a$, condition (19) requires there are no white particles in C_0 and no gray particles in C_1 . Figure 12 shows a hard-core configuration that satisfies this initial condition.

The output of this algorithm is a path ω from σ to **b**, which we construct as concatenation of 2*L* paths $\omega^{(1)}, \ldots, \omega^{(2L)}$. For every $j = 1, \ldots, 2L$, path $\omega^{(j)}$ goes from σ_j to σ_{j+1} , where we set $\sigma_1 := \sigma$, $\sigma_{2L+1} := \mathbf{b}$ and define for $j = 2, \ldots, 2L$

$$\sigma_j(v) := \begin{cases} \mathbf{b}(v) & \text{if } v \in c_2, \dots, c_{3j}, \\ \sigma(v) & \text{if } v \in c_{3j+1}, \dots, c_{6L+1}. \end{cases}$$



FIGURE 12 Example of hard-core configuration on the 6 × 9 triangular grid that satisfies (19) [Color figure can be viewed at wileyonlinelibrary.com]

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FIGURE 13 The configurations σ_1 and σ_2 corresponding to the initial configuration σ in Figure 12

We now describe in detail how to construct each of the paths $\omega^{(j)}$ for j = 1, ..., 2L. We distinguish 2 cases, depending on whether (a) σ_j has a vertical bridge in column c_{3j+2} or (b) not, see the 2 examples in Figure 13.

Consider case (a) first. First notice that the presence of a vertical (**c**-)bridge in column c_{3j+2} implies that all sites of the adjacent column c_{3j+3} must be empty in configuration σ_j .

We construct a path $\omega^{(j)} = (\omega_1^{(j)}, \dots, \omega_{2K+1}^{(j)})$ of length 2K + 1 (but possibly comprising void moves), with $\omega_1^{(j)} = \sigma_j$ and $\omega_{2K+1}^{(j)} = \sigma_{j+1}$. Denote by $o(j) \in \{0, 1\}$ the integer number such that $o(j) \equiv j \pmod{2}$. We first remove the 2 white particles in column c_{3j+2} that lie in row $r_{o(j)}$ and $r_{o(j)+2}$ in 2 successive steps, obtaining in this way configuration $o_3^{(j)}$, which is such that $H(\omega_3^{(j)}) = H(\omega_1^{(j)}) + 2$. We then repeat iteratively the following procedure to obtain the configuration $\omega_{i+1}^{(j)}$ from $\omega_i^{(j)}$ for all $i = 3, \dots, 2K - 1$:

- If $i \equiv 1 \pmod{2}$, consider the site $v \in c_{3j+1} \subset V_{\mathbf{b}}$ with coordinates (3j + 1, o(j) + i 2) and add a (black) particle there, obtaining in this way configuration $\omega_{i+1}^{(j)}$. Such a particle can be added since all its 6 neighboring sites are empty. More specifically, the 3 left ones have been (possibly) emptied along the path $\omega^{(j-1)}$, while the one in c_{3j+3} is empty by assumption and the other 2 sites on its right have been emptied in the previous steps of $\omega^{(j)}$. Since we added one particle, $H(\omega_{i+1}^{(j)}) = H(\omega_i^{(j)}) 1$.
- If $i \equiv 0 \pmod{2}$, consider the site $v \in c_{3j+2} \subset V_c$ with coordinates (3j+2, o(j)+i) and remove the (white) particle lying there, obtaining in this way configuration $\omega_{i+1}^{(j)}$, which is such that $H(\omega_{i+1}^{(j)}) = H(\omega_i^{(j)}) + 1$.

This procedure outputs configuration $\omega_{2K}^{(j)}$ which has no white particles in column c_{3j+2} and an empty site in column c_{3j+1} , the one with coordinates (3j + 1, 2K - 1 - o(j)). All the neighboring sites of this site are empty by construction and, adding a black particle in this site, we obtain configuration $\omega_{2K+1}^{(j)} = \sigma_{j+1}$, which is such that $H(\sigma_{j+1}) = H(\omega_{2K}^{(j)}) - 1$. The way the path $\omega^{(j)}$ is constructed shows that

$$H(\sigma_{j+1}) = H(\sigma_j),$$

since we added exactly K (black) particles in column c_{3j+1} and removed exactly K (white) particles in columns c_{3j+2} . Moreover,

$$\Phi_{\omega^{(j)}} = \max_{\eta \in \omega^{(j)}} H(\eta) = H(\sigma_j) + 2 \tag{20}$$

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since along the path $\omega^{(j)}$ every particle removal is followed by a particle addition, except at the beginning when we remove 2 particles consecutively.

Consider now case (b). We claim that, since there is no vertical (**c**-)bridge in column c_{3j+2} , there exists a site v^* in column c_{3j+1} with at most one neighboring occupied site. First of all, all sites in column c_{3j} and c_{3j-1} have been emptied along the path $\omega^{(j-1)}$, so all sites in c_{3j+1} have no left neighboring sites occupied. Let us look now at the right neighboring sites. Since there is no vertical **c**-bridge in column c_{3j+2} , there exists an empty site in it, say w. Modulo relabeling the rows, we may assume that w has coordinates (3j + 2, o(j)), where o(j) is the integer in $\{0, 1\}$ such that $o(j) \equiv j \pmod{2}$. The site $v^* = (3j + 1, o(j) + 1)$ has then the desired property, since at most one of its 2 remaining right neighboring sites (those with coordinates (3j + 2, o(j) + 2) and (3j + 3, o(j) + 1), respectively) can be occupied, since they are also neighbors of each other.

We construct a path $\omega^{(j)} = (\omega_1^{(j)}, \dots, \omega_{2K+1}^{(j)})$ of length 2K + 1 (but possibly comprising void moves), with $\omega_1^{(j)} = \sigma_j$ and $\omega_{2K+1}^{(j)} = \sigma_{j+1}$. We then repeat iteratively the following procedure to obtain configuration $\omega_{i+1}^{(j)}$ from $\omega_i^{(j)}$ for all $i = 1, \dots, 2K$:

- If $i \equiv 1 \pmod{2}$, consider the 2 sites $(3j+2, o(j)+i+1) \in V_c$ and $(3j+3, o(j)+i) \in V_a$. Since they are neighboring sites, at most one of them is occupied. If they are both empty, we set $\omega_{i+1}^{(j)} = \omega_i^{(j)}$. If instead there is a particle in either of the 2, we remove it, obtaining in this way configuration $\omega_{i+1}^{(j)}$, which is such that $H(\omega_{i+1}^{(j)}) = H(\omega_i^{(j)}) + 1$.
- If $i \equiv 0 \pmod{2}$, consider the site $v \in c_{3j+1} \subset V_{\mathbf{b}}$ with coordinates (3j + 1, o(j) + i 1) and add a (black) particle there, obtaining in this way configuration $\omega_{i+1}^{(j)}$. Such a particle can be added since all its 6 neighboring sites are empty. More specifically, the 3 left ones have been (possibly) emptied along the path $\omega^{(j-1)}$, while the other 2 sites on its right have been emptied in the previous step of $\omega^{(j)}$. Since we added one particle, $H(\omega_{i+1}^{(j)}) = H(\omega_i^{(j)}) 1$.

The way the path $\omega^{(j)}$ is constructed shows that $H(\sigma_{j+1}) \leq H(\sigma_j)$, since the number of (black) particles added in column c_{3j+1} is greater than or equal to the number of (white/gray) particles removed in columns c_{3j+2} and c_{3j+3} . Moreover, along the path $\omega^{(j)}$ every particle removal (if any) is always followed by a particle addition, and hence

$$\Phi_{\omega^{(j)}} = \max_{\eta \in \omega^{(j)}} H(\eta) \le H(\sigma_j) + 1.$$
(21)

Consider now the path $\omega : \sigma \to \mathbf{b}$ created by concatenating $\omega^{(1)}, \dots, \omega^{(2L)}$, which are constructed either using the procedure in case (a) or that in case (b). First notice that, regardless of which procedure

has been used at step *j*, the inequality $H(\sigma_{j+1}) \le H(\sigma_j)$ holds for every j = 1, ..., 2L. Using this fact in combination with (20) and (21) shows that the path ω always satisfies

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$$\Phi_{\omega} \le H(\sigma) + 2.$$

Furthermore, in the special case in which σ has no vertical **c**-bridges, our procedure considers case (b) for every j = 1, ..., 2L and thus, by virtue of (21), the path ω satisfies

$$\Phi_{\omega} - H(\sigma) \le 1.$$

If the target configuration of the energy reduction algorithm by columns is the configuration **a** (or **c**) one should adjust the condition (19) on the initial condition accordingly, requiring that σ has no particles in columns c_1 and c_2 (columns c_0 and c_1 , respectively). The offset of rows and columns in the procedures described above should of course be tweaked appropriately.

We now use the energy reduction algorithms we just introduced to show that the lower bound for the communication height between \mathbf{a} and \mathbf{b} given in Proposition 3.4 is sharp, by explicitly giving a path that attains that value.

Proposition 3.5 (Reference path) In the energy landscape corresponding to the hard-core model on the $2K \times 3L$ triangular grid there exists a path ω^* : $\mathbf{a} \rightarrow \mathbf{b}$ in \mathcal{X} such that

$$\Phi_{\omega^*} - H(\mathbf{a}) = \min\{K, 2L\} + 1.$$

Proof We distinguish 2 cases, depending on whether (a) $K \leq 2L$ and (b) K > 2L. In either case we first construct a path $\omega^{(1)}$: $\mathbf{a} \to \sigma^*$ where σ^* is a configuration to which we can apply energy reduction algorithm by columns (rows, respectively), and then, using this latter, we produce a path $\omega^{(2)}$: $\sigma^* \to \mathbf{b}$. The desired path ω^* : $\mathbf{a} \to \mathbf{b}$ will then be the concatenation of the paths $\omega^{(1)}$ and $\omega^{(2)}$.

Figure 14 illustrates the reference path from **a** to **b** in case (a) for the 6×9 triangular grid, while Figure 15 depicts some snapshots of ω^* : **a** \rightarrow **b** in case (b) for the 10 \times 6 triangular grid.

For case (a), the configuration σ^* differs from **a** only in the sites of column c_3 and, specifically,

$$\sigma^*(v) := \begin{cases} \mathbf{a}(v) & \text{if } v \in V \setminus c_3 \\ 0 & \text{if } v \in c_3. \end{cases}$$

The path $\omega^{(1)} = (\omega_1^{(1)}, \dots, \omega_{K+1}^{(1)})$, with $\omega_1^{(1)} = \mathbf{a}$ and $\omega_{K+1}^{(1)} = \sigma^*$ can be constructed as follows. For $i = 1, \dots, K$, at step *i* we remove from configuration $\omega_i^{(1)}$ the particle in the site of coordinates (3, 2i-1), increasing the energy by 1 and obtaining in this way configuration $\omega_{i+1}^{(1)}$. Therefore the configuration σ^* is such that $H(\sigma^*) - H(\mathbf{a}) = K$ and $\Phi_{\omega^{(1)}} = H(\sigma^*) = H(\mathbf{a}) + K$.

The second path $\omega^{(2)}$: $\sigma^* \to \mathbf{b}$ is then constructed by means of the energy reduction algorithm by columns, which can be used since the configuration σ^* satisfies condition (19) and hence is a suitable initial configuration for the algorithm. Since configuration σ^* has no vertical **c**-bridges (see case (b) for the energy reduction algorithm by columns), the procedure guarantees that

$$\Phi_{\omega^{(2)}} = H(\sigma^*) + 1 = H(\mathbf{a}) + K + 1,$$

and, therefore, $\Phi_{\omega^*} = \max{\{\Phi_{\omega^{(1)}}, \Phi_{\omega^{(2)}}\}} = H(\mathbf{a}) + K + 1$ as desired.



FIGURE 14 Illustration of the reference path ω^* : $\mathbf{a} \rightarrow \mathbf{b}$ in the case $K \leq 2L$

 $= \omega_1^{(2)}$ $\omega_{2}^{(2)}$ а σ^{\ast} $\omega_{3}^{(2)}$ $\omega_{4}^{(2)}$ $\omega_{5}^{(2)}$ $\omega_{0}^{(2)}$ $\omega_{13}^{(2)}$ b

FIGURE 15 Illustration of the reference path ω^* : $\mathbf{a} \rightarrow \mathbf{b}$ in the case K > 2L

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For case (b), consider the configuration σ^* that differs from **a** only in the sites of the first horizontal stripe S_0 , namely

$$\sigma^*(v) := \begin{cases} \mathbf{a}(v) & \text{if } v \in V \setminus S_0 \\ 0 & \text{if } v \in S_0. \end{cases}$$

The path $\omega^{(1)} = (\omega_1^{(1)}, \dots, \omega_{2L+1}^{(1)})$, with $\omega_1^{(1)} = \mathbf{a}$ and $\omega_{2L+1}^{(1)} = \sigma^*$ can be constructed as follows. For $i = 1, \dots, 2L$, at step *i* we remove from configuration $\omega_i^{(1)}$ the first particle in lexicographic order in S_0 ,

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increasing the energy by 1 and obtaining in this way configuration $\omega_{i+1}^{(1)}$. Therefore the configuration σ^* is such that $H(\sigma^*) - H(\mathbf{a}) = 2L$ and $\Phi_{\omega^{(1)}} = H(\sigma^*) = H(\mathbf{a}) + 2L$.

The second path $\omega^{(2)}$: $\sigma^* \to \mathbf{b}$ is then constructed by means of the energy reduction algorithm by rows, which can be used since the configuration σ^* satisfies condition (18) and hence is a suitable initial configuration for the algorithm. The energy reduction algorithm by rows guarantees that

$$\Phi_{\omega^{(2)}} = H(\sigma^*) + 1 = H(\mathbf{a}) + 2L + 1.$$

and thus the conclusion follows, since $\Phi_{\omega^*} = \max{\{\Phi_{\omega^{(1)}}, \Phi_{\omega^{(2)}}\}} = H(\mathbf{a}) + 2L + 1.$

3.3 | Proof of Theorem 3.1

(i) In every hard-core configuration $\sigma \in \mathcal{X}$ each particle blocks exactly 6 triangles, so that the total number $b_{\Lambda}(\sigma)$ of blocked triangles in σ is given by

$$b_{\Lambda}(\sigma) = 6 \sum_{v \in V} \sigma(v) = -6H(\sigma).$$
(22)

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Since Λ has 12*KL* triangles in total and we must have $b_{\Lambda}(\sigma) \leq 12KL$, it readily follows that $\max_{\sigma \in \mathcal{X}} \sum_{v \in V} \sigma(v) \leq 2KL$. Configurations **a**, **b** and **c** attain this value in view of (2) and, hence, $\min_{\sigma \in \mathcal{X}} H(\sigma) = -2KL$.

Suppose by contradiction that there exists another configuration $\sigma \in \mathcal{X} \setminus \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}$ such that $H(\sigma) = -2KL$. In view of (22), this means that all the triangles are blocked in σ . Starting from any triangle and using iteratively the fact that blocked triangles sharing an edge must be of the same color (cf. Remark 1), it is easy to show by induction that all the blocked triangles are of the same color and thus $\sigma \in \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}$, which is a contradiction.

(ii) The proof of the identity involving $\Phi(\mathbf{a}, \mathbf{b}) - H(\mathbf{a})$ readily follows by combining the lower bound in Proposition 3.4 and the statement of Proposition 3.5; the remaining identities immediately follows from symmetry of the triangular grid.

(iii) We will show that for every hard-core configuration σ on the $2K \times 3L$ triangular grid with $\sigma \neq \mathbf{a}, \mathbf{b}, \mathbf{c}$, there exists a path ω from σ to one of the 3 stable configurations such that

$$\Phi_{\omega} - H(\sigma) \le \min\{K, 2L\}.$$

The idea is to construct such a path using the geometric features of the configuration σ and exploiting the energy reduction algorithms described earlier in this section. We distinguish 2 cases: (a) $K \le 2L$ and (b) K > 2L.

Consider case (a) first, where $K \le 2L$. We distinguish 2 sub-cases, depending on whether σ has at least one vertical bridge or not.

If σ has a vertical bridge in a vertical stripe *C*, then σ is a suitable starting configuration for the energy reduction algorithm, which yields a path ω that goes from σ to the stable configuration in $\{\mathbf{a}, \mathbf{b}, \mathbf{c}\}$ on which σ agrees in stripe *C*. The path ω constructed in this way is such that $\Phi_{\omega} - H(\sigma) \le 2$ and thus $\Phi(\sigma, \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}) - H(\sigma) \le 2 \le K \le \min\{K, 2L\}$, since by assumption *K* is an integer greater than 1.

Suppose now that there are no vertical bridges in σ . Since $\sigma \notin \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}$, which is the set of stable configurations in view of Theorem 3.1(i), configuration σ has a positive energy difference $\Delta H(\sigma) > 0$. In view of (9), this means that there exists a vertical stripe C^* such that $\Delta H_{C^*}(\sigma) > 0$. Without loss

of generality, we may assume (modulo relabeling) that C^* is the vertical stripe C_1 , which consists of columns c_1, c_2 and c_3 . By definition of energy difference in a stripe, it follows that σ has at most K - 1 particles. Removing all the gray and white particles one by one, we construct a path $\omega^{(1)}$ from σ to a new configuration σ^* defined as

$$\sigma^*(v) := \begin{cases} \sigma(v) & \text{if } v \in V \setminus (c_2 \cup c_3), \\ 0 & \text{if } v \in c_2 \cup c_3. \end{cases}$$

Since σ has at most K - 1 particles in the vertical stripe C_1 , it follows that

$$H(\sigma^*) - H(\sigma) \le K - 1 \quad \text{and} \quad \Phi_{\omega^{(1)}} - H(\sigma) \le K - 1.$$
(23)

Since we remove all the gray particles from c_3 and all the white particles from c_2 , σ^* is a suitable starting configuration for the energy reduction algorithm by columns with target configuration **b**, in view of (19). We obtain in this way a second path $\omega^{(2)}$: $\sigma^* \to \mathbf{b}$, which is such that

$$\Phi_{\omega^{(2)}} - H(\sigma^*) \le 1, \tag{24}$$

thanks to the absence of vertical bridges in σ (and thus in σ^*). In view of (23) and (24), the path ω : $\sigma \rightarrow \mathbf{b}$ obtained by concatenating $\omega^{(1)}$ and $\omega^{(2)}$ is such that $\Phi_{\omega} - H(\sigma) \leq K$, and hence $\Phi(\sigma, \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}) - H(\sigma) \leq K$.

We remark that there is nothing special about **b** as target configuration of the path ω we just constructed. Indeed, by choosing the vertical stripe C^* with a different offset, we could have obtained a configuration σ^* which would have been a suitable initial configuration for the energy reduction algorithm by columns with target configuration **a** or **c**.

We now turn to case (b), in which K > 2L. Thanks to Lemma 3.3(i), there must be a horizontal stripe *S* on which σ does not have a horizontal bridge, otherwise $\sigma \in \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}$. In particular, σ has at most 2L - 1 particles on *S*, which without loss of generality we may assume to be S_0 . We construct a path $\omega^{(1)}$ from σ to a new configuration σ^* by removing all these particles one by one, so that $\Phi_{\omega^{(1)}} - H(\sigma) \leq 2L - 1$ and $H(\sigma^*) - H(\sigma) \leq 2L - 1$. Starting with configuration σ^* we can then use the energy reduction algorithm by rows to obtain a second path $\omega^{(2)}$ from σ^* to any of the 3 stable configurations. Since $\Phi_{\omega^{(2)}} - H(\sigma^*) \leq 1$, the path ω constructed by the concatenation of $\omega^{(1)}$ and $\omega^{(2)}$ satisfies $\Phi_{\omega} - H(\sigma) \leq 2L$ and thus $\Phi(\sigma, \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}) - H(\sigma) \leq 2L$.

4 | **PROOFS OF THE MAIN RESULTS**

This section is devoted to the proof of the 2 main results of the paper, namely Theorems 2.1 and 2.2

We first briefly recall in section 4.1 some model-independent results derived in [20] valid for any Metropolis Markov chain. We show how these general results can be used in combination with the structural properties of the energy landscape of the hard-core model on triangular grids, outlined in Theorem 3.1, to prove statements (i), (ii), and (iii) of Theorem 2.1 in section 4.2 and Theorem 2.2 in section 4.3. Although statements (iii) and (iv) of Theorem 2.1 both concern the asymptotic exponentiality of the scaled hitting times and look alike, their proofs slightly differ and for this reason that of statement (iv) is presented separately, in section 4.4, leveraging the symmetries that the state space \mathcal{X} inherits from the non-trivial automorphisms of the graph Λ .

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4.1 | Model-indepedent results for Metropolis Markov chains

We present here the model-independent results of the general framework developed in [20] only in a special case that is relevant for the tunneling times τ_b^a and $\tau_{\{b,c\}}^a$ under analysis. The more general statements can be found in [20], see Corollary 3.16, Theorem 3.17 and 3.19, and Proposition 3.18 and 3.20 therein.

Proposition 4.1 (Hitting time asymptotics [20]) Consider a non-empty subset $A \subset \mathcal{X}$ and $\sigma \in \mathcal{X} \setminus A$ and the following 2 conditions:

$$\Phi(\sigma, A) - H(\sigma) = \max_{\eta \in \mathcal{X} \setminus A} \Phi(\eta, A) - H(\eta),$$
(25)

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and

$$\Phi(\sigma, A) - H(\sigma) > \max_{\eta \in \mathcal{X} \setminus A, \, \eta \neq \sigma} \Phi(\eta, A \cup \{\sigma\}) - H(\eta).$$
⁽²⁶⁾

(i) If (25) holds for the pair (σ , A), then, setting $\Gamma := \Phi(\sigma, A) - H(\sigma)$, we have that for any $\varepsilon > 0$

$$\lim_{\beta \to \infty} \mathbb{P} \Big(e^{\beta(\Gamma - \varepsilon)} < \tau_A^{\sigma} < e^{\beta(\Gamma + \varepsilon)} \Big) = 1, \qquad and \qquad \lim_{\beta \to \infty} \frac{1}{\beta} \log \mathbb{E} \tau_A^{\sigma} = \Gamma$$

(ii) If (26) holds for the pair (σ , A), then

$$\frac{\tau_A^{\sigma}}{\mathbb{E}\tau_A^{\sigma}} \xrightarrow{d} \operatorname{Exp}(1), \quad \text{as } \beta \to \infty.$$

More precisely, there exist 2 functions $k_1(\beta)$ *and* $k_2(\beta)$ *with* $\lim_{\beta \to \infty} k_1(\beta) = 0$ *and* $\lim_{\beta \to \infty} k_2(\beta) = 0$ *such that for any* s > 0

$$\left|\mathbb{P}\left(\frac{\tau_A^{\sigma}}{\mathbb{E}\tau_A^{\sigma}} > s\right) - e^{-s}\right| \le k_1(\beta)e^{-(1-k_2(\beta))s}.$$

Condition (25) says that the initial configuration σ has an energy barrier separating it from the target subset *A* that is maximum over the entire energy landscape. Informally, this means that all other "valleys" (or more formally *cycles*, see definition in Manzo and coworkers [17]) of the energy landscape are not deeper than the one where the Markov chain starts; for this reason, the authors in [20] refer to (25) as "absence of deep cycles". On the other hand, condition (26) guarantees that from any configuration $\eta \in \mathcal{X}$ the Markov chain $\{X_t^{\beta}\}_{t \in \mathbb{N}}$ reaches the set $A \cup \{\sigma\}$ on a time scale strictly smaller than that at which the transition from σ to *A* occurs. We remark that both these conditions are sufficient, but not necessary, see [20] for further discussion.

For the proof of Theorem 2.2, we will also need the following proposition, which is also a general result concerning the asymptotic behavior of mixing time and spectral gap of any Metropolis Markov chain.

Proposition 4.2 (Mixing time asymptotics [20, Proposition 3.24]) For any $0 < \varepsilon < 1$

$$\lim_{\beta \to \infty} \frac{1}{\beta} \log t_{\beta}^{\min}(\epsilon) = \lim_{\beta \to \infty} -\frac{1}{\beta} \log \rho_{\beta} = \Gamma^*,$$

where $\Gamma^* := \max_{\eta \in \mathcal{X}, \eta \neq \sigma} \Phi(\eta, \sigma) - H(\eta)$ for any stable configuration $\sigma \in \mathcal{X}^s$. Furthermore, there exist 2 positive constants $0 < c_1 \le c_2 < \infty$ independent of β such that for every $\beta \ge 0$

$$c_1 e^{-\beta \Gamma^*} \le \rho_\beta \le c_2 e^{-\beta \Gamma^*}$$

4.2 | Proofs of Theorem 2.1(i)–(iii)

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From Theorem 3.1(iii) it immediately follows that

$$\max_{\sigma \neq \mathbf{a}, \mathbf{b}, \mathbf{c}} \Phi(\sigma, \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}) - H(\sigma) \le \min\{K, 2L\}.$$
(27)

Furthermore, we claim that the following identity holds:

$$\max_{\sigma \neq \mathbf{b}, \mathbf{c}} \Phi(\sigma, \{\mathbf{b}, \mathbf{c}\}) - H(\sigma) = \min\{K, 2L\} + 1.$$
(28)

First notice that since $\mathbf{a} \in \mathcal{X} \setminus {\mathbf{b}, \mathbf{c}}$, we have

$$\max_{\sigma \neq \mathbf{b}, \mathbf{c}} \Phi(\sigma, \{\mathbf{b}, \mathbf{c}\}) - H(\sigma) \ge \Phi(\mathbf{a}, \{\mathbf{b}, \mathbf{c}\}) - H(\mathbf{a}) = \min\{K, 2L\} + 1.$$

In order to prove that identity (28) holds, we need to show that this lower bound is sharp. In particular, we need to show that $\Phi(\sigma, {\mathbf{b}, \mathbf{c}}) - H(\sigma) \le \min{\{K, 2L\}} + 1$ for every configuration $\sigma \ne \mathbf{a}, \mathbf{b}, \mathbf{c}$, but we will actually prove a stronger inequality, namely

$$\Phi(\sigma, \mathbf{b}) - H(\sigma) \le \min\{K, 2L\} + 1, \quad \forall \sigma \in \mathcal{X} \setminus \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}.$$
(29)

In section 3.3 we introduced a iterative procedure that builds a path from any configuration σ to the set of stable configuration \mathcal{X}^s . More specifically, inspecting the proof of Theorem 3.1(iii), we notice that every configuration $\sigma \neq \mathbf{a}$, **b**, **c** can be reduced either directly to **b**, or otherwise to **a** or **c**, depending on its geometrical features. If σ can be reduced directly to **b**, then we prove therein that $\Phi(\sigma, \mathbf{b}) - H(\sigma) \leq \min\{K, 2L\}$. If not, then σ has to display a vertical **a**- or **c**-bridge and $K \leq 2L$. In the proof of Theorem 3.1(iii) we construct a path ω from σ to **a** (respectively, **c**) such that $\Phi_{\omega} \leq H(\sigma) + 2$, which, concatenated with the reference path from **a** to **b** (exhibited in Proposition 3.5) or the analogous reference path from **c** to **b**, shows that $\Phi(\sigma, \mathbf{b}) \leq \max\{H(\sigma) + 2, \Phi(\mathbf{a}, \mathbf{b})\}$. Thus,

$$\Phi(\sigma, \mathbf{b}) - H(\sigma) \le \max\{2, \Phi(\mathbf{a}, \mathbf{b}) - H(\sigma)\} \le \max\{2, \Phi(\mathbf{a}, \mathbf{b}) - H(\mathbf{a})\} = \max\{2, \min\{K, 2L\} + 1\}$$
$$\le \min\{K, 2L\} + 1,$$

which implies that inequality (29) holds. In view of (28), the pair $(\mathbf{a}, \{\mathbf{b}, \mathbf{c}\})$ then satisfies condition (25), since

$$\Phi(\mathbf{a}, \{\mathbf{b}, \mathbf{c}\}) - H(\mathbf{a}) = \min\{K, 2L\} + 1 = \max_{\sigma \neq \mathbf{b}, \mathbf{c}} \Phi(\sigma, \{\mathbf{b}, \mathbf{c}\}) - H(\sigma),$$

and Proposition 4.1(i) then yields statements (i) and (ii) of Theorem 2.1. Furthermore, by combining the latter identity and inequality (27), we obtain

$$\Phi(\mathbf{a}, \{\mathbf{b}, \mathbf{c}\}) - H(\mathbf{a}) = \min\{K, 2L\} + 1 > \min\{K, 2L\} \ge \max_{\sigma \neq \mathbf{a}, \mathbf{b}, \mathbf{c}} \Phi(\sigma, \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}) - H(\sigma)$$

and thus condition (26) holds for the pair (**a**, {**b**, **c**}). Proposition 4.1(ii) then yields the asymptotic exponentiality of the rescaled tunneling time $\tau^{\mathbf{a}}_{(\mathbf{b},\mathbf{c})}/\mathbb{E}\tau^{\mathbf{a}}_{(\mathbf{b},\mathbf{c})}$, that is

$$\frac{\tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}}{\mathbb{E}\tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}} \xrightarrow{d} \operatorname{Exp}(1), \quad \text{as } \beta \to \infty,$$
(30)

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proving Theorem 2.1(iii).

Consider now the other tunneling time $\tau_{\mathbf{b}}^{\mathbf{a}}$. From inequality (29) it immediately follows that

$$\max_{\sigma \neq \mathbf{b}} \Phi(\sigma, \mathbf{b}) - H(\sigma) \le \min\{K, 2L\} + 1,$$

which, in view of Proposition 3.5, implies that

$$\Phi(\mathbf{a}, \mathbf{b}) - H(\mathbf{a}) = \min\{K, 2L\} + 1 = \max_{\sigma \neq \mathbf{b}} \Phi(\sigma, \mathbf{b}) - H(\sigma)$$

Hence the pair (**a**, {**b**}) satisfies condition (25) and statements (i) and (ii) of Theorem 2.1 for the tunneling time $\tau_{\mathbf{b}}^{\mathbf{a}}$ immediately follow from Proposition 4.1(i).

4.3 | Proof of Theorem 2.2

The proof readily follows from Proposition 4.2, since by combining inequality (29) and Theorem 3.1(ii) we get

$$\Gamma^* = \max_{\sigma \neq \mathbf{b}} \Phi(\sigma, \mathbf{b}) - H(\sigma) = \min\{K, 2L\} + 1.$$

4.4 | Asymptotic exponentiality of the tunneling time $\tau_{\rm b}^{\rm a}$

The pair $(\mathbf{a}, \{\mathbf{b}\})$ does not satisfy condition (26), due to the presence of a deep cycle (the one where configuration \mathbf{c} lies) different from the initial configuration \mathbf{a} lies. Indeed, $\Phi(\mathbf{a}, \mathbf{b}) - H(\mathbf{a}) \not\leq \Phi(\mathbf{c}, \mathbf{b}) - H(\mathbf{c})$, as shown in Theorem 3.1(ii). Hence, the proof of Theorem 2.1(iv) does not follow from the general results outlined in Proposition 4.1, as in the case of statement (iii), but leverages in a crucial way the structure of the state space \mathcal{X} .

In view of the intrinsic symmetry of a triangular grid Λ , it is intuitive that the energy landscape \mathcal{X} on which the Markov chain $\{X_t^{\beta}\}_{t\in\mathbb{N}}$ evolves is highly symmetric, as witnessed by Figure 3. In this subsection, we show that the $2K \times 3L$ triangular grid has nontrivial automorphisms and discuss the consequences of this fact for the state space \mathcal{X} . We then leverage these symmetries to derive properties for the tunneling time τ_b^a (Proposition 4.3) and a stochastic representation for this latter (Corollary 4.4), and, ultimately, to prove the asymptotic exponentiality of the scaled hitting time $\tau_b^a/\mathbb{E}\tau_b^a$ in the limit $\beta \to \infty$, that is, Theorem 2.1(iv).

For every k = 0, ..., 6L - 1, the axial symmetry with respect to column c_k is the permutation $\xi_k : V \to V$ that maps site (i, j) into site (i, 2k - j), see Figure 16 for an example. In any such axial

FIGURE 16 A hard-core configuration on the 6×9 triangular grid Λ before (left) and after (right) the axial symmetry with respect to column c_8 , highlighted as dashed red vertical line, which maps column c_i into c_{16-i} for every $j = 0, \dots, 16$ and column c_{17} into itself. This axial symmetry induces an automorphism $\xi_{a,b}$ of the triangular grid Λ and, in particular, maps gray sites into black sites (and vice-versa) while white sites are only permuted [Color figure can be viewed at wileyonlinelibrary.com]

symmetry neighboring sites are mapped into neighboring sites, namely any pair of sites u, v form an edge if and only if the sites $\xi_k(u), \xi_k(v)$ form an edge. Hence, ξ_k is an automorphism of the graph Λ for every $k = 0, \dots, 6L - 1$. Each of these axial symmetries swaps 2 of the 3 components while mapping the third one to itself. Specifically,

$$\begin{cases} \xi_k(V_{\mathbf{a}}) = V_{\mathbf{a}}, \ \xi_k(V_{\mathbf{b}}) = V_{\mathbf{c}}, \ \xi_k(V_{\mathbf{c}}) = V_{\mathbf{b}}, & \text{if } k \equiv 0 \pmod{3}, \\ \xi_k(V_{\mathbf{a}}) = V_{\mathbf{c}}, \ \xi_k(V_{\mathbf{b}}) = V_{\mathbf{b}}, \ \xi_k(V_{\mathbf{c}}) = V_{\mathbf{a}}, & \text{if } k \equiv 1 \pmod{3}, \\ \xi_k(V_{\mathbf{a}}) = V_{\mathbf{b}}, \ \xi_k(V_{\mathbf{b}}) = V_{\mathbf{a}}, \ \xi_k(V_{\mathbf{c}}) = V_{\mathbf{c}}, & \text{if } k \equiv 2 \pmod{3}. \end{cases}$$
(31)

As illustrated by the next proposition, these axial symmetries of Λ induce automorphisms of the state space diagram \mathcal{X} corresponding to the hard-core dynamics on Λ . Hence, the state space \mathcal{X} is highly symmetric, as clearly visible in Figure 3, which shows the state space diagram of the hard-core model on the 4×6 triangular grid Λ . Leveraging the symmetry of \mathcal{X} , we construct a coupling between different copies of the Markov chain $\{X_t^{\beta}\}_{t\in\mathbb{N}}$ and prove in this way properties of the first hitting time $\tau^{a}_{\{\mathbf{h}\,\mathbf{c}\}}$.

Proposition 4.3 (Tunneling time properties) Let $\{X_t^{\beta}\}_{t \in \mathbb{N}}$ be the Metropolis Markov chain corresponding to the hard-core dynamics on the $2K \times 3L$ triangular grid. Then, for every $\beta > 0$,

(i) The random variable $X_{\tau^{\mathbf{a}}_{[\mathbf{b},\mathbf{c}]}}$ has a uniform distribution over $\{\mathbf{b},\mathbf{c}\}$;

(ii)
$$\tau^{\mathbf{a}}_{(\mathbf{b},\mathbf{c})} \stackrel{a}{=} \tau^{\mathbf{b}}_{(\mathbf{a},\mathbf{c})} \stackrel{a}{=} \tau^{\mathbf{c}}_{(\mathbf{a},\mathbf{b})}$$

(ii) $\tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}} = \tau_{\{\mathbf{a},\mathbf{c}\}}^{\mathbf{b}} = \tau_{\{\mathbf{a},\mathbf{b}\}}^{\mathbf{c}};$ (iii) The random variables $\tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}}$ and $X_{\tau_{\{\mathbf{b},\mathbf{c}\}}}^{\mathbf{a}}$ are independent.

Proof For the purpose of this proof it is enough to consider 3 axial symmetries that cover the 3 cases in (31) and thus we denote $\xi_{\mathbf{b},\mathbf{c}} := \xi_0, \xi_{\mathbf{a},\mathbf{c}} := \xi_1$, and $\xi_{\mathbf{a},\mathbf{b}} := \xi_2$. The automorphism $\xi_{\mathbf{b},\mathbf{c}} : V \to V$ induces a permutation $\overline{\xi}$ of the collection \mathcal{X} of hard-core configurations on Λ . More precisely, $\overline{\xi}$ maps the hard-core configuration $\sigma \in \mathcal{X}$ into a new configuration $\overline{\xi}(\sigma)$ defined as $(\overline{\xi}(\sigma))(v) = \sigma(\xi_{\mathbf{b},\mathbf{c}}(v))$ for every $v \in V$. In fact, $\overline{\xi}$ is an automorphism of the state space diagram, seen as a graph with vertex set \mathcal{X} and such that any pair of hard-core configurations $\sigma, \sigma' \in \mathcal{X}$ is connected by an edge if and only if σ and σ' differ in no more than one site, that is, $\|\sigma - \sigma'\| \leq 1$. By construction,

$$\overline{\xi}(\mathbf{b}) = \mathbf{c}, \quad \overline{\xi}(\mathbf{c}) = \mathbf{b}, \quad \text{and} \quad \overline{\xi}(\mathbf{a}) = \mathbf{a}.$$
 (32)

Assume the Metropolis Markov chain $\{X_t^{\beta}\}_{t\in\mathbb{N}}$ on Λ starts in configuration **a** at time 0. Let $\{Y_t^{\beta}\}_{t\in\mathbb{N}}$ be the Markov chain that mimics the moves of the Markov chain $\{X_t^{\beta}\}_{t\in\mathbb{N}}$ via the automorphism $\overline{\xi}$, that is, set $Y_t^{\beta} := \overline{\xi}(X_t^{\beta})$ for every $t \in \mathbb{N}$. For notational compactness, we suppress in this proof the dependence on β of these 2 Markov chains. For any pair of hard-core configurations $\sigma, \sigma' \in \mathcal{X}$, any transition of the chain Y_t^{β} from $\eta = \overline{\xi}(\sigma)$ to $\eta' = \overline{\xi}(\sigma')$ is feasible and occurs with the same probability as the transition from σ to σ' , since $\overline{\xi}$ is an automorphism. Therefore, the Markov chains $\{X_t\}_{t\in\mathbb{N}}$ and $\{Y_t\}_{t\in\mathbb{N}}$ are 2 copies of the hard-core dynamics on Λ living in the same probability space, and we have then defined in this way a coupling between them. In view of (32), this coupling immediately implies that the Markov chain $\{X_t\}_{t\in\mathbb{N}}$ started at **a** hits configuration **b** precisely when the chain $\{Y_t\}_{t\in\mathbb{N}}$ hits **c**. Hence,

$$\mathbb{P}\left(X_{\tau^{\mathbf{a}}_{[\mathbf{b},\mathbf{c}]}}=\mathbf{b},\ \tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}\leq t\right)=\mathbb{P}\left(\overline{\xi}(X_{\tau^{\mathbf{a}}_{[\mathbf{b},\mathbf{c}]}})=\overline{\xi}(\mathbf{b}),\ \tau^{\overline{\xi}(\mathbf{a})}_{\overline{\xi}(\{\mathbf{b},\mathbf{c}\})}\leq t\right)=\mathbb{P}\left(Y_{\tau^{\mathbf{a}}_{[\mathbf{b},\mathbf{c}]}}=\mathbf{c},\ \tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}\leq t\right).$$
(33)

Taking the limit $t \to \infty$ in (33), we obtain

$$\mathbb{P}\Big(X_{\tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}}=\mathbf{b}\Big)=\mathbb{P}\Big(Y_{\tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}}=\mathbf{c}\Big).$$

Using the fact that $\{X_t\}_{t\in\mathbb{N}}$ and $\{Y_t\}_{t\in\mathbb{N}}$ have the same statistical law, being 2 copies of the same Markov chain, it then follows that the random variable $X_{\tau^a_{(\mathbf{b},\mathbf{c})}}$ has a uniform distribution over $\{\mathbf{b},\mathbf{c}\}$, that is property (i). In particular,

$$\mathbb{P}\Big(X_{\tau^{\mathbf{a}}_{(\mathbf{b},\mathbf{c})}} = \mathbf{b}\Big) = \frac{1}{2}.$$
(34)

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Let $\hat{\xi}$ be the permutation of \mathcal{X} induced by the automorphism $\xi_{\{\mathbf{a},\mathbf{c}\}} \circ \xi_{\{\mathbf{a},\mathbf{b}\}}$. Constructing the coupling using $\hat{\xi}$ and arguing as above, we can deduce that

$$\mathbb{P}\Big(X_{\tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}}=\mathbf{b},\ \tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}\leq t\Big)=\mathbb{P}\Big(\hat{\xi}(X_{\tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}})=\hat{\xi}(\mathbf{b}),\ \tau^{\hat{\xi}(\mathbf{a})}_{\hat{\xi}(\{\mathbf{b},\mathbf{c}\})}\leq t\Big)=\mathbb{P}\Big(Y_{\tau^{\mathbf{b}}_{\{\mathbf{c},\mathbf{a}\}}}=\mathbf{c},\ \tau^{\mathbf{b}}_{\{\mathbf{c},\mathbf{a}\}}\leq t\Big),$$

and

$$\mathbb{P}\Big(X_{\tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}}=\mathbf{c},\ \tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}\leq t\Big)=\mathbb{P}\Big(\hat{\xi}(X_{\tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}})=\hat{\xi}(\mathbf{c}),\\ \tau^{\hat{\xi}(\mathbf{a})}_{\hat{\xi}(\{\mathbf{b},\mathbf{c}\})}\leq t\Big)=\mathbb{P}\Big(Y_{\tau^{\mathbf{b}}_{\{\mathbf{c},\mathbf{a}\}}}=\mathbf{a},\ \tau^{\mathbf{b}}_{\{\mathbf{c},\mathbf{a}\}}\leq t\Big).$$

Summing side by side these latter 2 identities yields that for every $t \ge 0$

$$\mathbb{P}\left(\tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}} \leq t\right) = \mathbb{P}\left(\tau_{\{\mathbf{c},\mathbf{a}\}}^{\mathbf{b}} \leq t\right),$$

proving property (ii). Note that

$$\mathbb{P}\left(\tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}} \leq t\right) = \mathbb{P}\left(X_{\tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}}} = \mathbf{b}, \ \tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}} \leq t\right) + \mathbb{P}\left(X_{\tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}}} = \mathbf{c}, \ \tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}} \leq t\right) = 2 \cdot \mathbb{P}\left(X_{\tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}}} = \mathbf{b}, \ \tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}} \leq t\right),$$
(35)

where the last passage follows from (33) using again the fact that $\{X_t\}_{t \in \mathbb{N}}$ and $\{Y_t\}_{t \in \mathbb{N}}$ have the same statistical law. Combining identities (34) and (35), we obtain that for every $t \ge 0$,

$$\mathbb{P}\Big(X_{\tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}}=\mathbf{b},\ \tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}\leq t\Big)=\mathbb{P}\Big(X_{\tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}}=\mathbf{b}\Big)\cdot\mathbb{P}\Big(\tau^{\mathbf{a}}_{\{\mathbf{b},\mathbf{c}\}}\leq t\Big),$$

that is property (iii).

The next corollary shows how the symmetries of the hard-core dynamics on a triangular grid Λ derived in Proposition 4.3 can be used to obtain a stochastic representation for the tunneling time $\tau_{\mathbf{b}}^{\mathbf{a}}$, that will be crucial to prove Theorem 2.1(iv). The underlying idea is that, on the time-scale at which the transition from **a** to **b** occurs, the evolution of $\{X_t^{\beta}\}_{t \in \mathbb{N}}$ can be represented by a 3-state Markov chain with a complete graph as state space diagram whose states correspond to the 3 valleys/cycles around the stable configurations **a**, **b**, and **c**. Similar ideas have been successfully used to describe metastability and tunneling phenomena in [1, 13, 14, 25].

Corollary 4.4 (Stochastic representation of the tunneling time $\tau_{\mathbf{b}}^{\mathbf{a}}$) Let $\{\tau^{(i)}\}_{i\in\mathbb{N}}$ be a sequence of *i.i.d. random variables with common distribution* $\tau \stackrel{d}{=} \tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}}$ and \mathcal{G} an independent geometric random variable with success probability 1/2, namely $\mathbb{P}(\mathcal{G} = m) = 2^{-m}$, for $m \ge 1$. Then,

$$\tau_{\mathbf{b}}^{\mathbf{a}} \stackrel{d}{=} \sum_{i=1}^{\mathcal{G}} \tau^{(i)},\tag{36}$$

and, in particular, $\mathbb{E}\tau_{\mathbf{b}}^{\mathbf{a}} = 2 \frac{1}{d} \mathbb{E}\tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}}$. Furthermore, if additionally there exists a non-negative random variable Y such that $\tau/\mathbb{E}\tau \to Y$ as $\beta \to \infty$, then

$$\frac{\tau_{\mathbf{b}}^{\mathbf{a}}}{\mathbb{E}\tau_{\mathbf{b}}^{\mathbf{a}}} \xrightarrow{d} \frac{1}{\mathbb{E}\mathcal{G}} \sum_{i=1}^{\mathcal{G}} Y^{(i)}, \quad \text{as } \beta \to \infty,$$
(37)

where $\{Y^{(i)}\}_{i\in\mathbb{N}}$ is a sequence of *i.i.d.* random variables distributed as Y.

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Proof Let \mathcal{G} be the random variable counting the number of non-consecutive visits of the Markov chain to $\{\mathbf{a}, \mathbf{c}\}$ until **b** is hit for the first time (counting the initial configuration **a** as first visit). In view of Proposition 4.3(i), the random variable \mathcal{G} is geometrically distributed with success probability $\frac{1}{2}$, with distribution $\mathbb{P}(\mathcal{G} = m) = 2^{-m}$, for $m \ge 1$. In particular, \mathcal{G} it does not depend on the inverse temperature β . The amount of time it takes for the Markov chain started in a stable configuration to hit any of the other 2 stable configurations does not depend on the initial stable configuration, by virtue of Proposition 4.3(ii). In view of these considerations and using the independence property in Proposition 4.3(iii), we deduce the stochastic representation (36) for the tunneling time $\tau_{\mathbf{b}}^{\mathbf{a}}$. The identity $\mathbb{E}\tau_{\mathbf{b}}^{\mathbf{a}} = 2 \cdot \mathbb{E}\tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}}$ then immediately follows from Wald's identity, since both \mathcal{G} and $\tau_{\{\mathbf{b},\mathbf{c}\}}^{\mathbf{a}}$ have finite expectation and $\mathbb{E}\mathcal{G} = 2$.

Lastly, we turn to the proof of the limit in distribution (37). Denoting by $\mathcal{L}_A(s) = \mathbb{E}(e^{-sA})$, with $s \ge 0$, the Laplace transform of a random variable A, the stochastic representation (36) yields $\mathcal{L}_{\tau_b^a} = G_{\mathcal{G}}(\mathcal{L}_\tau(s))$, where $G_{\mathcal{G}}(\cdot)$ is the probability generating function of the random variable \mathcal{G} , that is, $G_{\mathcal{G}}(z) = \mathbb{E}(z^{\mathcal{G}})$ for every $z \in [0, 1]$. By assumption $\mathcal{L}_{\tau/\mathbb{E}\tau}(s) \to \mathcal{L}_Y(s)$ as $\beta \to \infty$. Using the fact that $\mathbb{E}\tau_b^a = \mathbb{E}\tau \cdot \mathbb{E}\mathcal{G}$ we obtain

$$\mathcal{L}_{\tau_{\mathbf{b}}^{\mathbf{a}}/\mathbb{E}\tau_{\mathbf{b}}^{\mathbf{a}}} = G_{\mathcal{G}}\left(\mathcal{L}_{\tau/\mathbb{E}\tau}(s/\mathbb{E}\mathcal{G})\right) \xrightarrow{\beta \to \infty} G_{\mathcal{G}}\left(\mathcal{L}_{Y}(s/\mathbb{E}\mathcal{G})\right).$$

and the continuity theorem for Laplace transforms yields the conclusion.

Proof of Theorem 2.1(iv) Corollary 4.4 yields

$$\frac{\tau_{\mathbf{b}}^{\mathbf{a}}}{\mathbb{E}\tau_{\mathbf{b}}^{\mathbf{a}}} \xrightarrow{d} \frac{1}{2} \sum_{i=1}^{\operatorname{Geo}(1/2)} Y^{(i)}, \quad \text{as } \beta \to \infty,$$

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where $\{Y^{(i)}\}_{i \in \mathbb{N}}$ are i.i.d. exponential random variables, in view of (30). The statement in Theorem 2.1(iv) then follows by noticing that a geometric sum of i.i.d. exponential random variables scaled by its mean is also exponentially distributed with unit mean.

ACKNOWLEDGMENTS

The author has been supported by NWO grants 639.033.413 and 680.50.1529 and is grateful to F.R. Nardi, S.C. Borst, and J.S.H. van Leeuwaarden for the precious feedback on this work.

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How to cite this article: Zocca A. Tunneling of the hard-core model on finite triangular lattices. *Random Struct Alg.* 2019;55:215–246. https://doi.org/10.1002/rsa.20795